

Inverse Laplace Transform - If $f^*(s)$ denotes the Laplace transform of $f(t)$, then $f(t)$ is called the inverse Laplace transform of $f^*(s)$ i.e.

$$\text{if } L\{f(t)\} = f^*(s) \\ \text{then } L^{-1}\{f^*(s)\} = f(t)$$

Two particular

$$L^{-1}\left\{\frac{1}{s-a}\right\} = e^{at}, \quad L^{-1}\left\{\frac{a}{s^2+a^2}\right\} = \sin at$$

Properties of Inverse Laplace Transform -

(1) Linearity Property - If $f_i(t)$ is the inverse L.T. of $f_i^*(s)$, then for constants C_1, C_2, \dots

$$L^{-1}\left\{\sum_{i=1}^n C_i f_i^*(s)\right\} = \sum_{i=1}^n C_i L^{-1}\{f_i^*(s)\} = \sum_{i=1}^n C_i f_i(t)$$

(ii) Inverse L.T. of derivatives - If $L^{-1}\{f^*(s)\} = f(t)$

then $L^{-1}\left\{\frac{d^n}{ds^n} f^*(s)\right\} = (-1)^n t^n f(t)$

Proof - We have

$$L\{t^n f(t)\} = (-1)^n \frac{d^n}{ds^n} f^*(s)$$

Therefore $L^{-1}\left\{\frac{d^n}{ds^n} f^*(s)\right\} = (-1)^n t^n f(t)$

(iii) Inverse L.T. of Integrals - If $L^{-1}\{f^*(s)\} = f(t)$

then $L^{-1}\left[\int_s^\infty f^*(u) du\right] = \frac{f(t)}{t}$

Proof - Since we have

$$L\left\{\frac{f(t)}{t}\right\} = \int_s^\infty f^*(u) du, \text{ provided } \lim_{t \rightarrow 0} \frac{f(t)}{t} \text{ exists}$$

$$\therefore L^{-1}\left\{\int_s^\infty f^*(u) du\right\} = \frac{f(t)}{t}$$

(iv) Change of Origin property - If $L^{-1}\{f^*(s)\} = f(t)$

then $L^{-1}\{f^*(s-a)\} = e^{at} f(t), s > a$

Proof - We have

$$f^*(s) = \int_0^\infty e^{-st} f(t) dt$$

$$\therefore f^*(s-a) = \int_0^\infty e^{-(s-a)t} f(t) dt$$

$$= \int_0^\infty e^{-st} e^{at} f(t) dt = L\{e^{at} f(t)\}$$

$$\text{So, } L^{-1}\{f^*(s-a)\} = e^{at} f(t)$$

(V) Change of scale property - If $L^{-1}\{f^*(s)\} = f(t)$
then

$$L^{-1}\{f^*(as)\} = \frac{1}{a} f\left(\frac{t}{a}\right)$$

Proof - We have $f^*(s) = \int_0^{\infty} e^{-st} f(t) dt$

$$\begin{aligned} \text{Now } f^*(as) &= \int_0^{\infty} e^{-ast} f(t) dt \\ &= \int_0^{\infty} e^{-sx} f\left(\frac{x}{a}\right) \frac{dx}{a} \\ &= \frac{1}{a} \int_0^{\infty} e^{-st} f\left(\frac{t}{a}\right) dt = \frac{1}{a} L\left\{f\left(\frac{t}{a}\right)\right\} \end{aligned}$$

Therefore, $L^{-1}\{f^*(as)\} = \frac{1}{a} f\left(\frac{t}{a}\right)$ Proved

(VI) The displacement theorem - If $L^{-1}\{f^*(s)\} = f(t)$
then $L^{-1}\{e^{-\lambda s} f^*(s)\} = \begin{cases} f(t-\lambda), & t > \lambda \\ 0, & t < \lambda \end{cases}$

Proof - We have $f^*(s) = \int_0^{\infty} e^{-st} f(t) dt$

$$\begin{aligned} \therefore e^{-\lambda s} f^*(s) &= \int_0^{\infty} e^{-(t+\lambda)s} f(t) dt \\ &= \int_0^{\infty} e^{-xs} f(x-\lambda) dx \\ &= \int_{\lambda}^{\infty} e^{-st} f(t-\lambda) dt \\ &= \int_0^{\lambda} e^{-st} \cdot 0 dt + \int_{\lambda}^{\infty} e^{-st} f(t-\lambda) dt \end{aligned}$$

$\therefore L^{-1}\{e^{-\lambda s} f^*(s)\} = \begin{cases} f(t-\lambda), & t > \lambda \\ 0, & t < \lambda \end{cases}$ Proved

Partial Fraction Technique - This technique is used to find the inverse Laplace transforms of a rational function such as $\frac{G(s)}{Q(s)}$, where $G(s)$ and $Q(s)$ are the polynomials in s and the degree of $G(s)$ is less than that of $Q(s)$. The following exercises will show how the theory of partial fractions can be used in finding inverse Laplace transform.

Exercise-1 Find $L^{-1}\left\{\frac{s+2}{(s-4)(s-6)}\right\}$

Solution - Here the degree of $G(s) = s+2$ is one and that of $Q(s) = (s-4)(s-6)$ is two. So we can apply this technique.

Writing

$$\frac{s+2}{(s-4)(s-6)} = \frac{A}{s-4} + \frac{B}{s-6} \quad (1)$$

Multiplying both sides of (1) by $(s-4)$ and putting $s=4$, we get

$$-\frac{6}{2} = A \Rightarrow A = -3$$

Now again multiplying both sides of (1) by $(s-6)$ and putting $s=6$, we get

$$\frac{8}{2} = B \Rightarrow B = 4$$

Therefore,

$$\frac{G(s)}{Q(s)} = -\frac{3}{s-4} + \frac{4}{s-6}$$

Now using the table of Laplace transform, we get

$$\begin{aligned} \mathcal{L}^{-1}\left\{\frac{G(s)}{a(s)}\right\} &= -3 \mathcal{L}^{-1}\left[\frac{1}{s-4}\right] + 4 \mathcal{L}^{-1}\left[\frac{1}{s-6}\right] \\ &= -3e^{4t} + 4e^{6t} \end{aligned}$$

Exercise-2 Find $\mathcal{L}^{-1}\left\{\frac{s+1}{s(s+2)}\right\}$

Solution - Writing

$$\frac{s+1}{s(s+2)} \equiv \frac{A}{s} + \frac{B}{s+2} \quad (1)$$

To obtain value of A , we multiply both sides of (1) by s and put $s=0$, so that

$$\frac{1}{2} = A \Rightarrow A = 1/2$$

Now to obtain value of B , we multiply both sides of (1) by $s+2$ and put $s=-2$, we get

$$\frac{1}{2} = B \Rightarrow B = 1/2$$

Therefore,

$$\frac{s+1}{s(s+2)} = \frac{1}{2s} + \frac{1}{2(s+2)}$$

$$\text{Now, } \mathcal{L}^{-1}\left[\frac{s+1}{s(s+2)}\right] = \frac{1}{2} \mathcal{L}^{-1}\left[\frac{1}{s}\right] + \frac{1}{2} \mathcal{L}^{-1}\left[\frac{1}{s+2}\right]$$

$$= \frac{1}{2} + \frac{1}{2}e^{-2t}, \text{ using table of L.T.}$$

Exercise-3 Find $\mathcal{L}^{-1}\left\{\frac{a^2}{s(s+a)^2}\right\}$

$$\text{Solution - Writing } \frac{a^2}{s(s+a)^2} \equiv \frac{A}{s} + \frac{B}{s+a} + \frac{C}{(s+a)^2}$$

$$\text{or } a^2 = (s+a)^2 A + s(s+a)B + sC \quad (1)$$

Now comparing the coefficients of s^2 , s and constant term on both the sides of (1), we get

$$A+B=0$$

$$2aA+aB+C=0$$

$$a^2A=a^2$$

Therefore, $A=1$, $B=-1$ and $C=-a$

So that

$$\frac{a^2}{s(s+a)^2} \equiv \frac{1}{s} - \frac{1}{s+a} - \frac{a}{(s+a)^2}$$

Now $L^{-1}\left\{\frac{a^2}{s(s+a)^2}\right\} = 1 - e^{-at} - at e^{-at}$; using table of L.T.

Heaviside Theorem - Let $G(s)$ and $Q(s)$ be two polynomials in s where the degree of $G(s)$ is less than that of $Q(s)$, then the inverse Laplace transform of rational function $\frac{G(s)}{Q(s)}$ may be written as

$$L^{-1}\left[\frac{G(s)}{Q(s)}\right] = \sum_{i=1}^k \frac{G(\beta_i)}{Q'(\beta_i)} e^{\beta_i t}$$

where the prime represents derivatives w.r.t. s , β_i represents i th zero/^{root} and k denotes the total number of distinct zeros/^{roots} of $Q(s)$.

Proof - Since $G(s)$ is a polynomial of degree less than that of $Q(s)$ and $Q(s)$ has k distinct zeros

$\beta_1, \beta_2, \dots, \beta_k$.

$$\therefore \frac{G(s)}{Q(s)} = \frac{G(s)}{(s-\beta_1)(s-\beta_2)\dots(s-\beta_k)} \equiv \frac{A_1}{s-\beta_1} + \frac{A_2}{s-\beta_2} + \dots + \frac{A_k}{s-\beta_k}$$

Multiplying both the sides by $(s - \beta_i)$ and putting $s = \beta_i$, we get

$$\begin{aligned}
 A_i &= \lim_{s \rightarrow \beta_i} \frac{G(s)(s - \beta_i)}{Q(s)} \\
 &= G(\beta_i) \lim_{s \rightarrow \beta_i} \frac{(s - \beta_i)}{Q(s)} \\
 &= G(\beta_i) \lim_{s \rightarrow \beta_i} \frac{1}{Q'(s)}, \text{ by applying L'Hospital Rule.} \\
 &= \frac{G(\beta_i)}{Q'(\beta_i)}
 \end{aligned}$$

$$\therefore \frac{G(s)}{Q(s)} = \frac{G(\beta_1)}{Q'(\beta_1)} \frac{1}{s - \beta_1} + \frac{G(\beta_2)}{Q'(\beta_2)} \frac{1}{s - \beta_2} + \dots + \frac{G(\beta_R)}{Q'(\beta_R)} \frac{1}{s - \beta_R}$$

$$\begin{aligned}
 \text{Now } L^{-1} \left[\frac{G(s)}{Q(s)} \right] &= \frac{G(\beta_1)}{Q'(\beta_1)} e^{\beta_1 t} + \frac{G(\beta_2)}{Q'(\beta_2)} e^{\beta_2 t} + \dots + \frac{G(\beta_R)}{Q'(\beta_R)} e^{\beta_R t} \\
 &= \sum_{i=1}^R \frac{G(\beta_i)}{Q'(\beta_i)} e^{\beta_i t} \quad \text{Proved.}
 \end{aligned}$$

Exercise - 1 By using Heaviside theorem find $L^{-1} \left\{ \frac{3s+1}{(s-1)(s^2+1)} \right\}$.

Solution Here $G(s) = 3s+1$ and $Q(s) = (s-1)(s^2+1)$
 Clearly, $Q(s)$ has three distinct roots $\beta_1 = 1, \beta_2 = i, \beta_3 = -i$
 Also $Q'(s) = \frac{d}{ds} (s^3 - s^2 + s - 1) = 3s^2 - 2s + 1$

$$\therefore \text{By Heaviside theorem } L^{-1} \left[\frac{3s+1}{(s-1)(s^2+1)} \right] = \frac{G(\beta_1)}{Q'(\beta_1)} e^{\beta_1 t} + \frac{G(\beta_2)}{Q'(\beta_2)} e^{\beta_2 t} + \frac{G(\beta_3)}{Q'(\beta_3)} e^{\beta_3 t}$$

$$= \frac{4}{2} e^t + \frac{3i+1}{-2(i+1)} e^{it} + \frac{1-3i}{2(i-1)} e^{-it}$$

$$= 2e^t - \frac{3i+1}{2(i+1)} e^{it} + \frac{1-3i}{2(i-1)} e^{-it} \quad \underline{\text{Ans.}}$$

Exercise-2 By using Heaviside theorem find

$$L^{-1} \left\{ \frac{2s^2 - 6s + 5}{s^3 - 6s^2 + 11s - 6} \right\}$$

Solution - Here $G(s) = 2s^2 - 6s + 5$ and

$$Q(s) = s^3 - 6s^2 + 11s - 6 = (s-1)(s-2)(s-3)$$

Clearly, $Q(s)$ has three distinct roots $\beta_1=1, \beta_2=2, \beta_3=3$
 and $Q'(s) = 3s^2 - 12s + 11$

Now by Heaviside theorem

$$L^{-1} \left[\frac{2s^2 - 6s + 5}{s^3 - 6s^2 + 11s - 6} \right] = \frac{1}{2} e^t - e^{2t} + \frac{5}{2} e^{3t} \quad \underline{\text{Ans.}}$$

Exercise-3 By using Heaviside theorem find

$$(i) L^{-1} \left[\frac{s^2 - s + 2}{s^3 + 4s^2 + 3s} \right] \quad (ii) L^{-1} \left[\frac{2s^2 + 5s - 4}{s^3 + s^2 - 2s} \right]$$

$$(iii) L^{-1} \left[\frac{3s^2 + 2s + 1}{s^5 - s} \right] \quad (iv) L^{-1} \left[\frac{s^2 - 3s}{s^3 + s^2 + s + 1} \right]$$

Solution - Try Yourself.

Convolution Theorem - Let $f(t)$ and $g(t)$ be two continuous functions. Also let $L[f(t)] = f^*(s)$ and $L[g(t)] = g^*(s)$. Then we know that

$$L[f(t) \otimes g(t)] = L \left[\int_0^t f(u) g(t-u) du \right] = f^*(s) g^*(s)$$

Therefore,

$$L^{-1}[f^*(s) \cdot g^*(s)] = \int_0^t f(u)g(t-u)du$$

This theorem is used to obtain inverse Laplace transform of a function which can be expressed as the product of two or more functions. The following exercises will clear the application of this theorem.

Exercise-1 By using convolution theorem find $L^{-1}\left[\frac{1}{(s-1)(s+2)}\right]$

Solution - Let

$$f^*(s) = \frac{1}{s-1} \quad \text{and} \quad g^*(s) = \frac{1}{s+2}$$

From the table of L.T., we get

$$f(t) = e^t \quad \text{and} \quad g(t) = e^{-2t}$$

$$\begin{aligned} \text{Now } L^{-1}\left[\frac{1}{(s-1)(s+2)}\right] &= \int_0^t f(u)g(t-u)du \\ &= \int_0^t e^u e^{-2(t-u)} du = e^{-2t} \int_0^t e^{3u} du \\ &= \frac{1}{3} (e^t - e^{-2t}) \end{aligned}$$

Exercise-2 By convolution theorem find $L^{-1}\left[\frac{s}{(s^2+a^2)^2}\right]$

Solution - Let

$$f^*(s) = \frac{s}{s^2+a^2} \quad \text{and} \quad g^*(s) = \frac{1}{s^2+a^2}$$

Obviously, $f(t) = \cos at$ and $g(t) = \frac{1}{a} \sin at$

$$\begin{aligned}
\text{Now } L^{-1} \left[\frac{s}{(s^2+a^2)^2} \right] &= \int_0^t f(u) g(t-u) du \\
&= \int_0^t \cos au \cdot \frac{1}{a} \sin a(t-u) du \\
&= \frac{1}{a} \int_0^t \cos au (\sin at \cos au - \cos at \sin au) du \\
&= \frac{1}{a} \sin at \int_0^t \cos^2 au du - \frac{1}{a} \cos at \int_0^t \sin au \cos au du \\
&= \frac{1}{2a} \sin at \int_0^t (1 + \cos 2au) du - \frac{1}{2a} \cos at \int_0^t \sin 2au du \\
&= \frac{1}{2a} \sin at \left[t + \frac{\sin 2at}{2a} \right] - \frac{1}{2a} \cos at \left(1 - \frac{\cos 2at}{2a} \right) \\
&= \frac{t \sin at}{2a} + \frac{\sin at \cdot 2 \sin at \cos at}{2a^2} -
\end{aligned}$$

Exercise-4 By applying convolution theorem, find the value of

$$\int_0^1 x^{m-1} (1-x)^{n-1} dx$$

Solution— Let us consider

$$f(t) = \int_0^t x^{m-1} (t-x)^{n-1} dx$$

$$= \int_0^t f_1(x) f_2(t-x) dx, \text{ where } f_1(t) = t^{m-1} \text{ and } f_2(t) = t^{n-1}$$

$$= f_1(t) \otimes f_2(t)$$

Therefore,

$$f^*(s) = f_1^*(s) \cdot f_2^*(s)$$

$$= \frac{\Gamma(m)}{s^m} \cdot \frac{\Gamma(n)}{s^n} = \frac{\Gamma(m)\Gamma(n)}{s^{m+n}}$$

$$\text{and } f(t) = \int_0^t x^{m-1} (t-x)^{n-1} dx = \Gamma(m)\Gamma(n) \mathcal{L}^{-1} \left[\frac{1}{s^{m+n}} \right]$$

$$= \frac{\Gamma(m)\Gamma(n)}{\Gamma(m+n)} t^{m+n-1}$$

Taking $t=1$, we get

$$\int_0^1 x^{m-1} (1-x)^{n-1} dx = \frac{\Gamma(m)\Gamma(n)}{\Gamma(m+n)} = B(m, n)$$

The Solution of Simple Differential Equations by L.T. -

Example-1 Find the general solution of the differential equation

$$y''(t) + R^2 y(t) = 0$$

Solution -

Taking Laplace Transform of both the sides

$$L[y''(t)] + R^2 L[y(t)] = 0$$

$$\text{or } s^2 y^*(s) - s y(0) - y'(0) + R^2 y^*(s) = 0$$

$$\text{Let } y(0) = A \text{ and } y'(0) = B$$

$$\therefore s^2 y^*(s) - A s - B + R^2 y^*(s) = 0$$

$$\text{or } [s^2 + R^2] y^*(s) = A s + B$$

$$\text{or } y^*(s) = A \frac{s}{s^2 + R^2} + B \frac{1}{s^2 + R^2}$$

$$= A \frac{s}{s^2 + R^2} + \frac{B}{R} \frac{R}{s^2 + R^2}$$

Now using the table of L.T., we have

$$y(t) = A L^{-1} \left\{ \frac{s}{s^2 + R^2} \right\} + \frac{B}{R} L^{-1} \left\{ \frac{R}{s^2 + R^2} \right\}$$

$$= A \cos Rt + \frac{B}{R} \sin Rt$$

Example-2 Find the solution of the differential equation

$$y''(t) - y'(t) - 6y(t) = 2$$

satisfying the initial conditions

$$y(0) = 1, y'(0) = 0$$

Solution - Taking Laplace transform of both the sides of differential equation we get

$$s^2 y^*(s) - s y(0) - y'(0) - s y^*(s) + y(0) - 6 y^*(s) = \frac{2}{s}$$

$$\text{or } s^2 Y^*(s) - s - s Y^*(s) + 1 = 6 Y^*(s) = \frac{2}{s}$$

$$\text{or } (s^2 - s - 6) Y^*(s) = \frac{2}{s} + s - 1$$

$$\text{or } (s^2 - s - 6) Y^*(s) = \frac{s^2 - s + 2}{s}$$

$$\text{or } Y^*(s) = \frac{s^2 - s + 2}{s(s-3)(s+2)} \equiv \frac{A}{s} + \frac{B}{s-3} + \frac{C}{s+2}$$

Multiplying both the sides by s and putting $s=0$ we get $A = -1/3$

Multiplying both the sides by $s-3$ and putting $s=3$ we get $B = 8/15$

Similarly, multiplying both the sides by $s+2$ and putting $s=-2$, we get $C = 4/5$

$$\text{So } Y^*(s) = -\frac{1}{3} \cdot \frac{1}{s} + \frac{8}{15} \cdot \frac{1}{s-3} + \frac{4}{5} \cdot \frac{1}{s+2}$$

Taking inverse L.T., we get

$$Y(t) = -\frac{1}{3} + \frac{8}{15} e^{3t} + \frac{4}{5} e^{-2t} \quad \underline{\text{Ans.}}$$

Example-3 Find the functions $Y(t)$ and $Z(t)$ that satisfy the following system of differential eqⁿ.

$$1. Y''(t) - Z''(t) + Z'(t) - Y(t) = e^t - 2$$

$$2. Y''(t) - Z''(t) - 2Y'(t) + Z(t) = -t$$

$$Y(0) = Y'(0) = Z(0) = Z'(0) = 0$$

Solution - Taking L.T. of both the differential equations and using the initial conditions, we get

$$s^2 Y^*(s) - s^2 Z^*(s) + s Z^*(s) - Y^*(s) = \frac{1}{s-1} - \frac{2}{s}$$

$$2s^2 Y^*(s) - s^2 Z^*(s) - 2s Y^*(s) + Z^*(s) = -\frac{1}{s^2}$$

$$\text{or } (s^2 - 1) Y^*(s) - (s^2 - s) Z^*(s) = \frac{-s+2}{s(s-1)}$$

$$(2s^2 - 2s) Y^*(s) - (s^2 - 1) Z^*(s) = -\frac{1}{s^2}$$

$$\text{or } (\delta+1)Y^*(\delta) - \delta Z^*(\delta) = \frac{-\delta+2}{\delta(\delta-1)^2}$$

$$2\delta Y^*(\delta) - (\delta+1)Z^*(\delta) = -\frac{1}{\delta^2(\delta-1)}$$

Simplifying the above algebraic equation for $Y^*(\delta)$ and $Z^*(\delta)$, we get

$$Y^*(\delta) = \frac{1}{\delta(\delta-1)^2} \quad \text{and} \quad Z^*(\delta) = \frac{2\delta-1}{\delta^2(\delta-1)^2}$$

Taking the inverse L.T. of $Y^*(\delta)$ and $Z^*(\delta)$, we find

$$Y(t) = 1 - e^t + te^t$$

$$\text{and } Z(t) = -t + te^t \quad \underline{\text{Ans.}}$$

Problems—

Find the solution of the following differential equations—

(i) $y''(t) - k^2 y(t) = 0$ ($k \neq 0$)

(ii) $y''(t) - 2ky'(t) + k^2 y(t) = 0$

(iii) $y''(t) + k^2 y(t) = a$

(iv) $y''(t) + 2y'(t) + 2y(t) = 0$, $y(0) = 0$, $y'(0) = 1$

(v) $y''(t) + y'(t) = t^2 + 2t$, $y(0) = 4$, $y'(0) = -2$

(vi) $x'(t) + y'(t) + x(t) + y(t) = 1$

$$y'(t) - 2x(t) - y(t) = 0$$

$$x(0) = 0, \quad y(0) = 1$$