

### 3.7.3 Conditions for Causality and Stability in terms of Z-Transform :

We know that the condition for causality in terms of  $h(n)$  is,

$$h(n) = 0 \quad n < 0$$

...(3.7.4)

Here the condition  $n < 0$  indicates that value of  $h(n)$  for negative 'n' is zero. That  $h(n)$  is causal sequence. In Z-transforms we know that if a sequence is causal then the ROC is exterior part of circle having radius 'r'. Now the system transfer function is,

$$H(Z) = Z \{ h(n) \}$$

...(3.7.5)

Thus the condition for causality is that the ROC of system transfer function should be exterior part of circle having radius 'r' and  $r < \infty$ .

We have already studied the condition for stability. It is,

$$\sum_{n=-\infty}^{\infty} |h(n)| < \infty$$

...(3.7.6)

$\mathcal{Z}\{h(n)\} = H(Z) = \sum_{n=-\infty}^{\infty} h(n)Z^{-n}$  can be written as Z-Transform

Taking absolute value on both the sides,

$$|H(Z)| = \left| \sum_{n=-\infty}^{\infty} h(n)Z^{-n} \right| \quad (3.7.7)$$

Now the absolute value on a sum is always less than the sum of absolute value. (3.7.8)

$$|H(Z)| < \sum_{n=-\infty}^{\infty} |h(n)||Z^{-n}| \quad (3.7.9)$$

If we evaluate the Z-transform on the unit circle that means  $|Z^{-n}| = |Z| = 1$  then equation (3.7.9) becomes,

$$|H(Z)| < \sum_{n=-\infty}^{\infty} |h(n)| \quad (3.7.10)$$

According to Equation (3.7.6), if the system is BIBO stable then  $\sum_{n=-\infty}^{\infty} |h(n)| < \infty$ . Thus the

condition of stability in Z-domain is,

$|H(Z)| < \infty$  when evaluated on unit circle. (3.7.11)

That means the system transfer function should be finite if evaluated on unit circle.

Equation (3.7.6) gives the condition of stability in Z domain. *This condition requires that, unit circle must be present in the ROC of H(Z).* Otherwise we cannot find H(Z) on unit circle at all.

**Combined Condition :**

- (1) For a causal LSI system we know that ROC is exterior part of circle; that mean  $|Z| > |r|$
- (2) For the stable LSI system, ROC of H(Z) must include unit circle. Here unit circle is a circle having radius 1. Now consider we have a causal system having ROC as exterior part of circle with radius 'r'. Then for this system to be stable; it should include unit circle as shown in Fig. 3.7.1.

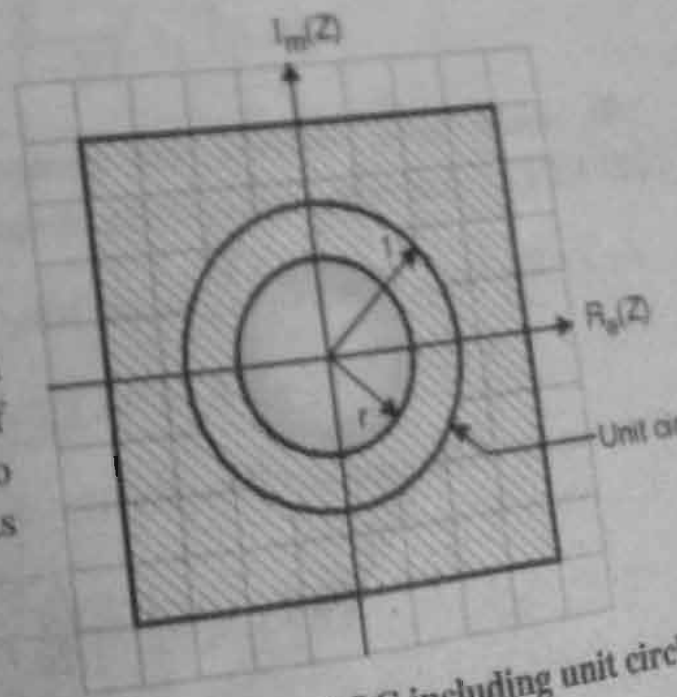


Fig. 3.7.1 : ROC including unit circle

Thus the combined condition for causal and stable LSI system is,

$$|Z| > r < 1$$

We know that,

- (i) ROC of  $H(Z)$  does not contain any poles.
- (ii) ROC of stable and causal LSI system includes the unit circle.

Thus we can state that ***all the poles of  $H(Z)$  of a causal and stable system are inside the unit circle.***

Ex. 3.7.9 : Consider the system  $H(Z) = \frac{1 - 2Z^{-1} + 2Z^{-2} - Z^{-3}}{(1 - Z^{-1})(1 - 0.5Z^{-1})(1 - 0.2Z^{-1})}$

with ROC :  $0.5 < |Z| < 1$ .

- (i) Sketch the pole-zero pattern. Is the system stable ?
- (ii) Determine the impulse response of system.

Soln. :

(i) **Pole-zero Pattern** : The given function is,

$$H(Z) = \frac{1 - 2Z^{-1} + 2Z^{-2} - Z^{-3}}{(1 - Z^{-1})(1 - 0.5Z^{-1})(1 - 0.2Z^{-1})}$$

To convert it into positive powers of  $Z$  we will multiply numerator and denominator by  $Z^3$ .

$$\therefore H(Z) = \frac{Z^3(1 - 2Z^{-1} + 2Z^{-2} - Z^{-3})}{Z(1 - Z^{-1})Z(1 - 0.5Z^{-1})Z(1 - 0.2Z^{-1})}$$

$$\therefore H(Z) = \frac{Z^3 - 2Z^2 + 2Z - 1}{(Z - 1)(Z - 0.5)(Z - 0.2)}$$

To obtain zeros, consider the numerator polynomial. We will obtain the roots  $Z^3 - 2Z^2 + 2Z - 1$ . Let us perform synthetic division.

$1 - 2 + 2 - 1 = 0$ . Thus  $(Z - 1)$  exists. Now dividing  $Z^3 - 2Z^2 + 2Z - 1$  by  $(Z - 1)$  we get,

$$Z^3 - 2Z^2 + 2Z - 1 = (Z - 1)(Z^2 - Z + 1)$$

Now we will obtain roots of  $Z^2 - Z + 1$

$$Z^2 - Z + 1 = \frac{-b \pm \sqrt{b^2 - 4ac}}{2a} = \frac{1 \pm \sqrt{1 - 4}}{2} = \frac{1}{2} \pm j \frac{\sqrt{3}}{2}$$

$$\therefore Z^2 - Z + 1 = \left(\frac{1}{2} + j \frac{\sqrt{3}}{2}\right) \left(\frac{1}{2} - j \frac{\sqrt{3}}{2}\right)$$

Thus Equation (1) becomes,

$$Z^3 - 2Z^2 + 2Z - 1 = (Z-1)\left(Z - \frac{1}{2} - j\frac{\sqrt{3}}{2}\right)\left(Z - \frac{1}{2} + j\frac{\sqrt{3}}{2}\right) \quad \dots(4)$$

Putting Equation (4) in Equation (2) we get,

$$H(Z) = \frac{(Z-1)\left(Z - \frac{1}{2} - j\frac{\sqrt{3}}{2}\right)\left(Z - \frac{1}{2} + j\frac{\sqrt{3}}{2}\right)}{(Z-1)(Z-0.5)(Z-0.2)}$$

$$\therefore H(Z) = \frac{\left(Z - \frac{1}{2} - j\frac{\sqrt{3}}{2}\right)\left(Z - \frac{1}{2} + j\frac{\sqrt{3}}{2}\right)}{(Z-0.5)(Z-0.2)} \quad \dots(5)$$

We have the standard equation of  $H(Z)$  in terms of poles and zeros,

$$H(Z) = \frac{(Z-Z_1)(Z-Z_2)}{(Z-P_1)(Z-P_2)} \quad \dots(6)$$

Comparing Equations (5) and (6) we can write,

$$\text{Zeros} \Rightarrow Z_1 = \frac{1}{2} + j\frac{\sqrt{3}}{2} \text{ and } Z_2 = \frac{1}{2} - j\frac{\sqrt{3}}{2}$$

$$\text{and Poles} \Rightarrow P_1 = 0.5 \text{ and } P_2 = 0.2$$

The pole-zero plot is shown in Fig. P. 3.7.9.

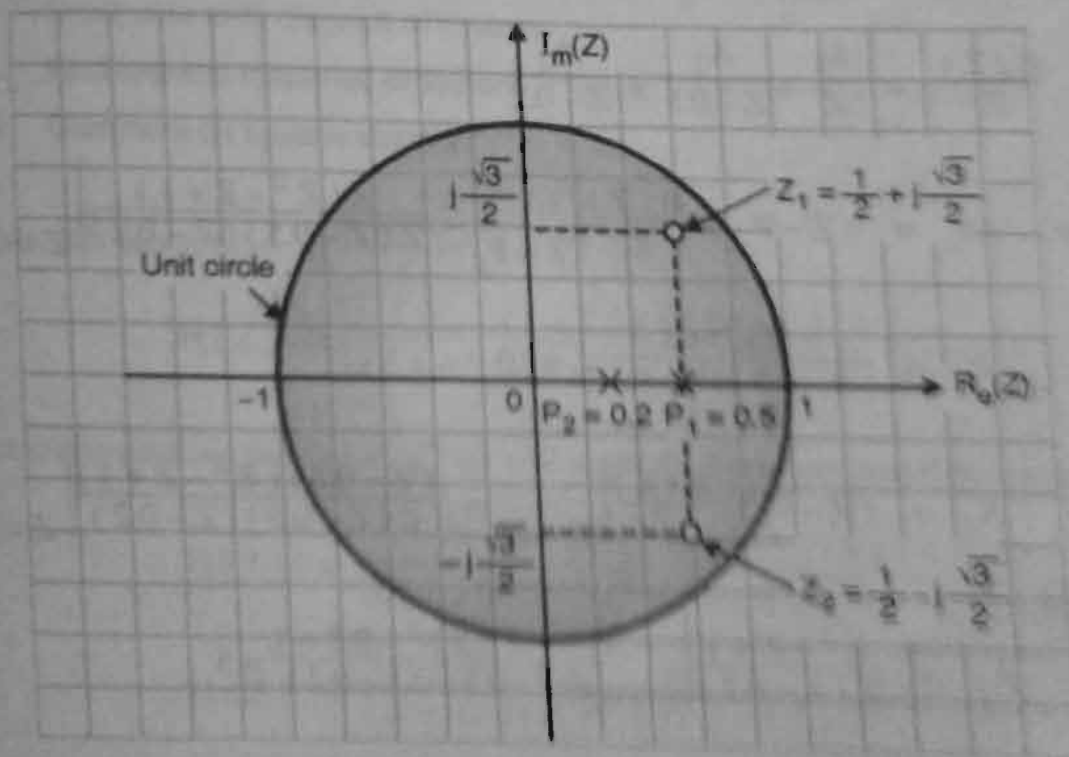


Fig. P. 3.7.9 : Pole-zero plot

(ii) **Impulse Response :**

Impulse response is denoted by  $h(n)$ . It is obtained by taking IZT of  $H(Z)$ .

We have,

$$H(Z) = \frac{\left(Z - \frac{1}{2} - j\frac{\sqrt{3}}{2}\right)\left(Z - \frac{1}{2} + j\frac{\sqrt{3}}{2}\right)}{(Z - 0.5)(Z - 0.2)}$$

$$\therefore H(Z) = \frac{Z^2 - Z + 1}{Z^2 - 0.7Z + 0.1}$$

Here  $M = N$ ; we want  $M < N$ . Thus multiplying and dividing by  $Z$ ,

$$H(Z) = \frac{Z(Z^2 - Z + 1)}{Z(Z^2 - 0.7Z + 0.1)}$$

$$\therefore \frac{H(Z)}{Z} = \frac{Z^2 - Z + 1}{Z(Z^2 - 0.7Z + 0.1)}$$

Now the degree of numerator ( $M$ ) is less than the degree of denominator ( $N$ ). So in proper form.

$$\therefore \frac{H(Z)}{Z} = \frac{Z^2 - Z + 1}{Z(Z - 0.5)(Z - 0.2)}$$

Here poles are  $P_1 = 0$ ,  $P_2 = 0.5$  and  $P_3 = 0.2$ .

We will write Equation (9) in partial fraction expansion form.

$$\therefore \frac{H(Z)}{Z} = \frac{A_1}{Z} + \frac{A_2}{Z - 0.5} + \frac{A_3}{Z - 0.2}$$

$$\text{Now } A_1 = (Z - P_1) \left. \frac{H(Z)}{Z} \right|_{Z=P_1} = \left. \frac{Z(Z^2 - Z + 1)}{Z(Z - 0.5)(Z - 0.2)} \right|_{Z=0}$$

$$\therefore A_1 = \frac{0 + 0 + 1}{(0 - 0.5)(0 - 0.2)} = 10$$

$$A_2 = (Z - P_2) \left. \frac{H(Z)}{Z} \right|_{Z=P_2} = \left. \frac{(Z - 0.5)(Z^2 - Z + 1)}{Z(Z - 0.5)(Z - 0.2)} \right|_{Z=0.5}$$

$$\therefore A_2 = \left. \frac{Z^2 - Z + 1}{Z(Z - 0.2)} \right|_{Z=0.5} = \frac{(0.5)^2 - 0.5 + 1}{0.5(0.5 - 0.2)} = 5$$

$$\text{and } A_3 = (Z - P_3) \left. \frac{H(Z)}{Z} \right|_{Z=P_3} = \left. \frac{(Z - 0.2)(Z^2 - Z + 1)}{Z(Z - 0.5)(Z - 0.2)} \right|_{Z=0.2}$$

$$\therefore A_3 = \left. \frac{Z^2 - Z + 1}{Z(Z - 0.5)} \right|_{Z=0.2} = \frac{(0.2)^2 - 0.2 + 1}{0.2(0.2 - 0.5)} = -14$$

Substituting these values in Equation (10) we get,

$$\frac{H(Z)}{Z} = \frac{10}{Z} + \frac{5}{Z-0.5} + \frac{(-14)}{Z-0.2}$$

$$\therefore H(Z) = 10 + \frac{5Z}{Z-0.5} - \frac{14Z}{Z-0.2}$$

The given ROC is  $0.5 < |Z| < 1$ . So all the terms are causal.

$$\therefore \mathcal{ZT} \{ 10 \} = 10 \mathcal{ZT} \{ 1 \} = 10 \delta(n)$$

$$\mathcal{ZT} \left\{ \frac{5Z}{Z-0.5} \right\} = 5 \mathcal{ZT} \left\{ \frac{Z}{Z-0.5} \right\} = 5 (0.5)^n u(n)$$

$$\mathcal{ZT} \left\{ \frac{-14Z}{Z-0.2} \right\} = -14 \mathcal{ZT} \left\{ \frac{Z}{Z-0.2} \right\} = -14 (0.2)^n u(n).$$

$$\therefore h(n) = 10 \delta(n) + 5 (0.5)^n u(n) - 14 (0.2)^n u(n)$$