

Unit -> 2

Subject -> Analog ckt

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Lecture 7 -> gain margin and phase margin

Gain Margin and Phase Margin

We know that one can determine whether a feedback amplifier is or is not stable by examining its loop gain $A\beta$ as a function of frequency. One of the simplest and most effective means for doing this is through the use of a bode plot for $A\beta$, such as the one shown in fig. 1 that can be because the phase approaches -360° the network examined is a fourth-order (one). The feedback amplifier whose loop gain is plotted in fig. 1 will be stable, since at the frequency of 180° phase shift, ω_{180} , the magnitude of the loop gain is less than (negative dB). The difference between the value of $|A\beta|$ at ω_{180} and unity called the gain margin, is usually expressed in decibels.

The gain margin represents the amount by which the loop gain can be increased with stability is maintained.

Feedback amplifiers are usually designed to have sufficient gain margin to allow for the inevitable changes in loop gain with the temperature, time and so on.

Another way to investigate the stability and to express in degree is to examine the bode plot at the frequency for which $|A\beta|=1$, which is the point at which the magnitude plot then crosses the 0-dB line. If at this frequency

the phase angle is (less) [In Magnitude] than 180° , then the amplifier is stable. This is the situation illustrated in Fig. The Difference between the phase angle at the frequency and 180° is termed the Phase Margin. On the other hand, If at the frequency of unity loop gain magnitude, the phase lag is in excess of 180° the amplifier will be Unstable.

